



Far-field maximal power absorption of a bulging cylindrical wave energy converter

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Context



A. Babarit, J. Singh, et al. "A numerical model for analysing the hydroelastic response of a flexible Electro Active Wave Energy Converter". In: *Journal of Fluid and Structures* 74 (2017), pp. 356–384

 Goal: open lightweight tool for the hydrodynamical design of WEC with non-trivial degrees of freedom.



Summary

Theory of far-field maximal absorption width

Implementation

Applications Floating buoy Bulging cylindrical WEC

Conclusion and perspectives







Strategy

- Linear potential flow in frequency domain.
- Energy balance:

$$\mathsf{captured} = \oint \mathsf{incoming} \mathsf{ and} \mathsf{ leaving} \mathsf{ waves}$$

For a given geometry, find the motion giving the best captured width.



Scheme adapted from (Babarit and Delhommeau 2015)



Preliminary definitions

Kochin function H

$$\Phi(R,\theta,z) = 4\pi \sqrt{\frac{1}{\lambda R}} H(\theta) f_0(z) e^{i\left(2\pi \frac{R}{\lambda} + \frac{\pi}{4}\right)} + O\left(\frac{1}{R^{\frac{3}{2}}}\right)$$

Complex-valued amplitudes of motions \hat{a}_j

Linear potential flow \Rightarrow linear combination of dofs $H = \sum_{j=1}^{n} \hat{a}_{j} H_{j}$



Absorption width

For a given motion $\hat{a} = (\hat{a}_j)_{j \in \{1,...,n\}}$:

$$\frac{W(\hat{a})}{8\pi k} = \Im\left(\sum_{j=1}^n \hat{a}_j H_j^*(\pi+\beta)\right) - k^2 \int_0^{2\pi} \left|\sum_{j=1}^n \hat{a}_j H_j(\theta)\right|^2 d\theta$$

Maximal absorption width

 $W^{\mathsf{optimal}} = \max_{\hat{a} \in \mathbb{C}^n} \left[W(\hat{a}) \right]$



Constraints on motion

Actually, \hat{a}^{optimal} might be unphysical.

Maximal absorption width under constraint

$$W^{\mathsf{optimal}} = \max_{\hat{a} \in \{\mathsf{adimissible motions}\}} [W(\hat{a})]$$

Example of constraints for a single degree of freedom:

 $|\hat{x}| = \max(|x(t)|)_{t \in [0,T]} < cst.$



Some previous works

- J.N. Newman. "Absorption of wave energy by elongated bodies". In: Applied Ocean Research 1.4 (1979), pp. 189–196
- ► FJM. Farley. "Wave energy conversion by flexible resonant rafts". In: Applied Ocean Research 4.1 (1982), pp. 57–63
- FJM. Farley. "Far-field theory of wave power capture by oscillating systems". In: Philosophical Transactions of the Royal Society A: Mathematical, Physical and Engineering Sciences 370 (2012), pp. 278–287
- J. Falnes and A. Kurniawan. "Fundamental formulae for wave-energy conversion". In: Royal Society open science 2.3 (2015), p. 140305
- A. Babarit. L'énergie des vagues: Ressource, technologies et performance. ISTE éditions, 2018
 MaREI





Structure of the code





Capytaine: a Python-based distribution of Nemoh

- ► Full rewrite of Nemoh in Fortran 90 + Python.
- Improving user interface, documentation and testing.
- Integration with Python ecosystem (here Scipy optimization algorithm).
- Experimental optimizations.

Openly available under GPL license:

- conda install -c conda-forge capytaine
- Documentation: https://ancell.in/capytaine/
- Source code: https://github.com/mancellin/capytaine/







Application to a floating buoy





Wave direction = 0 rad





Dotted line: unlimited motion.

Wave direction = 0 rad





Wave direction = 0 rad



Wave direction = 0 rad



Wave direction = 0 rad



Wavelengh = 5 m





Dotted line: unlimited motion.

Wavelengh = 5 m





Dotted line: unlimited motion.







Dotted line: unlimited motion.













Small scale model of bulging WEC:



$$\sin(1 \times 2\pi x/L)$$



Small scale model of bulging WEC:



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Small scale model of bulging WEC:







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Small scale model of bulging WEC:







Wave direction = 0 rad



Wave direction = 0 rad



Wave direction = 0 rad



Wave direction = 0 rad



Wave direction = 0 rad



Wave direction = 0 rad



Wavelength = $0.5 \times$ cylinder length



















Wavelength = $0.5 \times$ cylinder length



Wavelength = $0.5 \times$ cylinder length



Wavelength = $0.5 \times$ cylinder length







Perspectives

Continuing work at UCD:

- Comparison with equations of motion from (Babarit et al., 2017).
- Use of the actual modes of deformation of the S3 and parametric studies;

To-do:

- More physical constraints, including incoming wave height;
- Dedicated optimization algorithm?
- Analytical resolution of the optimization problem?



Conclusion

Proof-of-concept of a lightweight model for WECs design:

- Based on far-field radiated waves;
- Purely hydrodynamical;
- Few inputs: the geometry, the active dofs and their maximal amplitude;
- Including any non-trivial dofs.



Thank you for your attention!

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