

Bouncing and floating on a free surface: The kinematic match

Carlos Galeano-Rios

HyWEC 2

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Engineering and Physical Sciences Research Council

Experiments by Daniel Harris, Brown University

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Perfectly Hydrophobic Rigid Sphere



Perfectly Hydrophobic Rigid Sphere

in the contact area



Perfectly Hydrophobic Rigid Sphere

in the contact area



Perfectly **Hydrophobic**







Perfectly **Hydrophobic** Rigid **Sphere**

$$\begin{split} \Delta \phi &= 0, & z \leqslant 0, \\ \eta_t &= \frac{2}{Re} \Delta_H \eta + \phi_z, & z = 0, \\ \phi_t &= -\frac{1}{Fr} \eta + \frac{1}{We} \kappa [\eta] + \frac{2}{Re} \Delta_H \phi - p_s, & z = 0; \end{split}$$

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 $\phi =$ Velocity Potential

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$$\label{eq:phi} \begin{split} \phi &= \text{Velocity Potential} \\ \eta &= \text{Free Surface Elevation} \end{split}$$

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 ϕ = Velocity Potential η = Free Surface Elevation p_s = Pressure on Free Surface

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$\kappa = Curvature$

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 $\kappa = \text{Curvature}$ $Re = V_0 R_o / \nu$

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<u>A Non-local Formulation in Physical Space</u> $z \leqslant 0,$ $\Delta \phi = 0,$ $\eta_t = \frac{2}{Re} \Delta_H \eta + \phi_z$ z = 0, $\phi_t = -\frac{1}{Fr}\eta + \frac{1}{We} \kappa [\eta] + \frac{2}{Re}\Delta_H \phi - p_s, \qquad z = 0;$ subject to $\eta \to 0$ when $\sqrt{x^2 + y^2} \to \infty$ $\phi, \nabla \phi \to 0$ when $\sqrt{x^2 + y^2 + z^2} \to \infty$. $\phi_{z}(\mathbf{r}) = \frac{1}{2\pi} \lim_{\epsilon \to 0^{+}} \int_{\mathbb{R}^{2} \setminus B(\mathbf{r} \cdot \epsilon)} \frac{\phi(\mathbf{r}) - \phi(\mathbf{s})}{|\mathbf{r} - \mathbf{s}|^{3}} dA(\mathbf{s})$

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$$\mathbf{Q}W^{j+1} = F^j,$$

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$$\mathbf{Q} = \begin{bmatrix} \left(\mathbf{I} - \frac{2\delta t}{Re}\Delta_{H}\right) & -\delta tN & 0 & 0 & 0 \\ \delta t \left(\frac{1}{Fr}\mathbf{I} - \frac{1}{We}\Delta_{H}\right) & \left(\mathbf{I} - \frac{2\delta t}{Re}\Delta_{H}\right) & \delta t\mathbf{I} & 0 & 0 \\ 0 & 0 & -\delta t\frac{A}{M} & (1 + \delta tD) & 0 \\ 0 & 0 & 0 & -\delta t & 1 \end{bmatrix}$$

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$$W^{j+1} = \begin{bmatrix} \eta^{j+1} & \phi^{j+1} & p_s^{j+1} & h_t^{j+1} & h_t^{j+1} \end{bmatrix}^1,$$

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$$W^{j+1} = \begin{bmatrix} \eta^{j+1} & \phi^{j+1} & p_s^{j+1} & h_t^{j+1} & h_t^{j+1} \end{bmatrix}^{\mathrm{T}},$$
$$F^j = \begin{bmatrix} \eta^j & \left(\phi^j + \frac{1}{We} \left(\kappa - \Delta_H\right) \eta^{j+1}\right) & \left(h_t^j - \delta t \ \frac{1}{Fr}\right) & h^j \end{bmatrix}^{\mathrm{T}}$$

 $\boldsymbol{Q}_k W_k^{j+1} = F_k^j,$

$$\boldsymbol{Q}_{k}W_{k}^{j+1} = F_{k}^{j},$$

$$\boldsymbol{q}_{k} = \begin{bmatrix} \left(\boldsymbol{I}^{k'} - \frac{2\delta t}{Re}\Delta_{H}^{k'}\right) & -\delta t \ N & 0 & 0 & a_{k} \\ \delta t \left(\frac{1}{Fr}\boldsymbol{I}^{k'} - \frac{1}{We}\Delta_{H}^{k'}\right) & \left(\boldsymbol{I} - \frac{2\delta t}{Re}\Delta_{H}\right) & \delta t\boldsymbol{I}^{k} & 0 & b_{k} \\ 0 & 0 & -\delta t\frac{A^{k}}{M} & (1 + \delta tD) & 0 \\ 0 & 0 & 0 & -\delta t & 1 \end{bmatrix}$$

$$\begin{aligned} \mathbf{Q}_{k}W_{k}^{j+1} &= F_{k}^{j}, \\ \mathbf{Q}_{k} &= \begin{bmatrix} \left(\mathbf{I}^{k'} - \frac{2\delta t}{Re}\Delta_{H}^{k'}\right) & -\delta t \ N & 0 & 0 & a_{k} \\ \delta t \left(\frac{1}{Fr}\mathbf{I}^{k'} - \frac{1}{We}\Delta_{H}^{k'}\right) & \left(\mathbf{I} - \frac{2\delta t}{Re}\Delta_{H}\right) & \delta t \mathbf{I}^{k} & 0 & b_{k} \\ 0 & 0 & -\delta t \frac{A^{k}}{M} & (1 + \delta t D) & 0 \\ 0 & 0 & 0 & -\delta t & 1 \end{bmatrix} \\ W^{j+1} &= \begin{bmatrix} \eta^{j+1,k'} & \phi^{j+1} & p_{s}^{j+1,k} & h_{t}^{j+1} & h^{j+1} \end{bmatrix}^{\mathrm{T}}, \end{aligned}$$

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 $\boldsymbol{Q}_k W_k^{j+1} = F_k^j,$

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$$(\eta^j)^{\mathrm{T}} - \left(I^k - \frac{2\delta t}{Re}\Delta_H^k\right)(z_s^k)^{\mathrm{T}}$$

$$F_k^j = \begin{bmatrix} (\phi^j)^{\mathrm{T}} - \delta t \left\{\frac{1}{Fr}I^k(z_s^k)^{\mathrm{T}} - \frac{1}{We}(I^k((\kappa z_s)^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}})\right\} \\ h_t^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{We}(I^k((\kappa z_s)^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}})\right\} \\ h_t^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} - \frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\} \\ H_k^j - \delta t \left\{\frac{1}{Fr}H_k^j(z_s^k)^{\mathrm{T}} + z_s((k-1)\delta r)c_k^{\mathrm{T}}\right\}$$

$$\begin{aligned} \mathbf{Q}_{k}W_{k}^{j+1} &= F_{k}^{j}, \\ (\eta^{j})^{\mathrm{T}} - \left(\mathbf{I}^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)(z_{s}^{k})^{\mathrm{T}} \\ (\phi^{j})^{\mathrm{T}} - \delta t \left\{\frac{1}{Fr}\mathbf{I}^{k}(z_{s}^{k})^{\mathrm{T}} - \frac{1}{We}(\mathbf{I}^{k}((\kappa z_{s})^{k})^{\mathrm{T}} + z_{s}((k-1)\delta r)c_{k}^{\mathrm{T}})\right\} \\ h_{t}^{j} - \delta t \left\{\frac{1}{Fr}\right\} \\ a_{k} &= \left(\mathbf{I}^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)[1, 1, \dots, 1]^{\mathrm{T}}, \end{aligned}$$

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$$\begin{aligned} \mathbf{Q}_{k}W_{k}^{j+1} &= F_{k}^{j}, \\ & (\eta^{j})^{\mathrm{T}} - \left(\mathbf{I}^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)(z_{s}^{k})^{\mathrm{T}} \\ & (\phi^{j})^{\mathrm{T}} - \delta t \left\{\frac{1}{Fr}\mathbf{I}^{k}(z_{s}^{k})^{\mathrm{T}} - \frac{1}{We}(\mathbf{I}^{k}((\kappa z_{s})^{k})^{\mathrm{T}} + z_{s}((k-1)\delta r)c_{k}^{\mathrm{T}})\right\} \\ & h_{t}^{j} - \delta t \frac{1}{Fr} \\ & h_{t}^{j} - \delta t \frac{1}{Fr} \\ & h_{t}^{j} - \delta t \left(\frac{1}{Fr}\mathbf{I}^{k}[1, 1, \dots, 1]^{\mathrm{T}} - \frac{1}{We}c_{k}^{\mathrm{T}}\right), \\ & c_{k} = \frac{2k-1}{2k(\delta r)^{2}}e_{k+1} \end{aligned}$$

,

Superindex k

$$\begin{aligned} \mathbf{Q}_{k} W_{k}^{j+1} &= F_{k}^{j}, \\ (\eta^{j})^{\mathrm{T}} - \left(\mathbf{I}^{k} - \frac{2\delta t}{Re} \Delta_{H}^{k}\right) (z_{s}^{k})^{\mathrm{T}} \\ (\phi^{j})^{\mathrm{T}} - \delta t \left\{ \frac{1}{Fr} \mathbf{I}^{k} (z_{s}^{k})^{\mathrm{T}} - \frac{1}{We} (\mathbf{I}^{k} ((\kappa z_{s})^{k})^{\mathrm{T}} + z_{s} ((k-1)\delta r) c_{k}^{\mathrm{T}}) \right\} \\ h_{t}^{j} - \delta t \frac{1}{Fr} \\ h_{j}^{j} \\ a_{k} &= \left(\mathbf{I}^{k} - \frac{2\delta t}{Re} \Delta_{H}^{k}\right) [1, 1, \dots, 1]^{\mathrm{T}}, \qquad b_{k} = \delta t \left(\frac{1}{Fr} \mathbf{I}^{k} [1, 1, \dots, 1]^{\mathrm{T}} - \frac{1}{We} c_{k}^{\mathrm{T}}\right), \\ c_{k} &= \frac{2k - 1}{2k(\delta r)^{2}} e_{k+1} \end{aligned}$$

Superindex k we kept the first k columns

$$Q_{k}W_{k}^{j+1} = F_{k}^{j},$$

$$F_{k}^{j} = \begin{bmatrix} (\eta^{j})^{\mathrm{T}} - \left(I^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)(z_{s}^{k})^{\mathrm{T}} \\ (\phi^{j})^{\mathrm{T}} - \delta t \left\{\frac{1}{Fr}I^{k}(z_{s}^{k})^{\mathrm{T}} - \frac{1}{We}(I^{k}((\kappa z_{s})^{k})^{\mathrm{T}} + z_{s}((k-1)\delta r)c_{k}^{\mathrm{T}})\right\} \\ h_{t}^{j} - \delta t \frac{1}{Fr} \\ h_{j}^{j} \end{bmatrix}$$

$$a_{k} = \left(I^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)[1, 1, \dots, 1]^{\mathrm{T}}, \qquad b_{k} = \delta t \left(\frac{1}{Fr}I^{k}[1, 1, \dots, 1]^{\mathrm{T}} - \frac{1}{We}c_{k}^{\mathrm{T}}\right), \qquad c_{k} = \frac{2k-1}{2k(\delta r)^{2}}e_{k+1}$$

Superindex k' we kept the first k columns Superindex k'

$$Q_{k}W_{k}^{j+1} = F_{k}^{j},$$

$$(\eta^{j})^{\mathrm{T}} - \left(I^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)(z_{s}^{k})^{\mathrm{T}}$$

$$(\phi^{j})^{\mathrm{T}} - \delta t \left\{\frac{1}{Fr}I^{k}(z_{s}^{k})^{\mathrm{T}} - \frac{1}{We}(I^{k}((\kappa z_{s})^{k})^{\mathrm{T}} + z_{s}((k-1)\delta r)c_{k}^{\mathrm{T}})\right\}$$

$$h_{t}^{j} - \delta t \frac{1}{Fr}$$

$$a_{k} = \left(I^{k} - \frac{2\delta t}{Re}\Delta_{H}^{k}\right)[1, 1, ..., 1]^{\mathrm{T}}, \qquad b_{k} = \delta t \left(\frac{1}{Fr}I^{k}[1, 1, ..., 1]^{\mathrm{T}} - \frac{1}{We}c_{k}^{\mathrm{T}}\right),$$

$$c_{k} = \frac{2k - 1}{2k(\delta r)^{2}}e_{k+1}$$

Superindexkwe kept the first k columnsSuperindexk'we kept all but the first k columns





















Experiment by Dan Harris (Brown)

Droplets on a Shaking Free Surface




Each bounce triggers new waves



Each bounce triggers new waves Waves determine following bounces



This is a non-linear, non-smooth dynamical system

$0.4\,{\rm mm} < D < 1\,{\rm mm}$



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$0.4\,{\rm mm} < D < 1\,{\rm mm}$



This is a non-linear, non-smooth dynamical system

$0.4\,{\rm mm} < D < 1\,{\rm mm}$



$V_z \approx 10 \,\mathrm{cm/s}$

This is a non-linear, non-smooth dynamical system

$0.4\,{\rm mm} < D < 1\,{\rm mm}$

 $\lambda \approx 5 \,\mathrm{mm}$

$V_z \approx 10 \,\mathrm{cm/s}$

 $e \approx 2 \mu \mathrm{m}$

This is a non-linear, non-smooth dynamical system

$0.4\,{\rm mm} < D < 1\,{\rm mm}$

 $\lambda \approx 5\,\mathrm{mm}$

 $e \approx 2 \mu \mathrm{m}$

$V_z \approx 10 \,\mathrm{cm/s}$

$f = 40 \,\mathrm{Hz}$

This is a non-linear, non-smooth dynamical system

$0.4\,{\rm mm} < D < 1\,{\rm mm}$

 $\lambda \approx 5 \,\mathrm{mm}$

$V_z \approx 10 \,\mathrm{cm/s}$

 $e \approx 2 \mu \mathrm{m}$

 $f = 40 \,\mathrm{Hz}$

 $A \approx 10 \,\mu\mathrm{m}$

This is a non-linear, non-smooth dynamical system





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Non-wetting impact of a sphere onto a bath and its application to bouncing droplets

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 $V_x \lesssim 1.5 \,\mathrm{cm/s}$

 $V_z \approx 10 \,\mathrm{cm/s}$



Video: Dan Harris & John Bush

Walker

 $V_z \approx 10 \,\mathrm{cm/s}$

$0.4\,\mathrm{mm} < D < 1\,\mathrm{mm}$

 $V_x \lesssim 1.5 \,\mathrm{cm/s}$

 $V_z \approx 10 \,\mathrm{cm/s}$

$0.4\,\mathrm{mm} < D < 1\,\mathrm{mm}$

 $\lambda \approx 5 \,\mathrm{mm}$































Quasi-normal free-surface impacts, capillary rebounds and application to Faraday walkers

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Ratcheting droplet pairs

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Thanks for your attention

Video: Dan Harris & John Bush

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