

# Wave-Structure interaction in shallow water

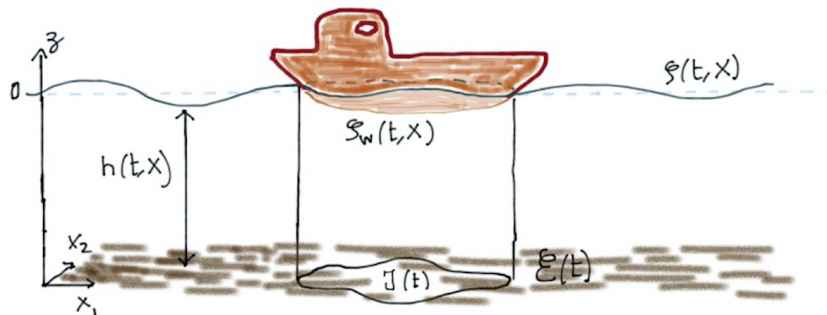
David Lannes  
IMB, Université de Bordeaux et CNRS

HYWEC 2, Bordeaux, 2019

# Outline

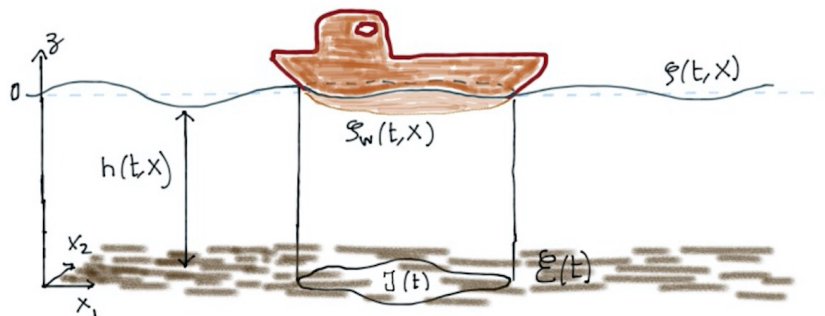
- General approach

## General approach



Floating device: ship or wave energy convertor

# General approach



Floating device: ship or wave energy convertor

## Notation

If  $f$  is defined on  $\mathbb{R}^d$ , we write

$$f_i = f|_{\mathcal{I}}$$

In the fluid domain  $\Omega_t$

$$\partial_t \mathbf{U} + \mathbf{U} \cdot \nabla_{X,z} \mathbf{U} = -\frac{1}{\rho} \nabla_{X,z} P - g \mathbf{e}_z$$

$$\operatorname{div} \mathbf{U} = 0,$$

$$\operatorname{curl} \mathbf{U} = 0$$

In the fluid domain  $\Omega_t$

$$\begin{aligned}\partial_t \mathbf{U} + \mathbf{U} \cdot \nabla_{X,z} \mathbf{U} &= -\frac{1}{\rho} \nabla_{X,z} P - g \mathbf{e}_z \\ \operatorname{div} \mathbf{U} &= 0, \\ \operatorname{curl} \mathbf{U} &= 0\end{aligned}$$

At the surface

$$\boxed{\forall X \in \mathcal{E}(t),} \quad \underline{P}(t, X) = P_{\text{atm}},$$

In the fluid domain  $\Omega_t$

$$\begin{aligned}\partial_t \mathbf{U} + \mathbf{U} \cdot \nabla_{X,z} \mathbf{U} &= -\frac{1}{\rho} \nabla_{X,z} P - g \mathbf{e}_z \\ \operatorname{div} \mathbf{U} &= 0, \\ \operatorname{curl} \mathbf{U} &= 0\end{aligned}$$

At the surface

$$\begin{aligned}\boxed{\forall X \in \mathcal{E}(t)}, & \quad \underline{P}(t, X) = P_{\text{atm}}, \\ \forall X \in \mathbb{R}^d, & \quad \partial_t \zeta - \underline{U} \cdot \underline{N} = 0 \quad ,\end{aligned}$$

In the fluid domain  $\Omega_t$

$$\partial_t \mathbf{U} + \mathbf{U} \cdot \nabla_{X,z} \mathbf{U} = -\frac{1}{\rho} \nabla_{X,z} P - g \mathbf{e}_z$$

$$\operatorname{div} \mathbf{U} = 0,$$

$$\operatorname{curl} \mathbf{U} = 0$$

At the surface

$$\boxed{\forall X \in \mathcal{E}(t),}$$

$$P(t, X) = P_{\text{atm}},$$

$$\forall X \in \mathbb{R}^d, \quad \partial_t \zeta - \underline{U} \cdot N = 0 \quad ,$$

At the bottom

$$U_b \cdot N_b = 0.$$



In the fluid domain  $\Omega_t$

$$\begin{aligned}\partial_t \mathbf{U} + \mathbf{U} \cdot \nabla_{X,z} \mathbf{U} &= -\frac{1}{\rho} \nabla_{X,z} P - g \mathbf{e}_z \\ \operatorname{div} \mathbf{U} &= 0, \\ \operatorname{curl} \mathbf{U} &= 0\end{aligned}$$

At the surface

$$\begin{aligned}\boxed{\forall X \in \mathcal{E}(t)}, & \quad \underline{P}(t, X) = P_{\text{atm}}, \\ \forall X \in \mathbb{R}^d, & \quad \partial_t \zeta - \underline{U} \cdot \underline{N} = 0 \quad ,\end{aligned}$$

At the bottom

$$U_b \cdot N_b = 0.$$

Constraint in the interior domain

The surface of the fluid coincides with the wetted portion of the body

$$\zeta_i = \zeta_w$$

## Coupling(s)

Interior/Exterior coupling on  $\Gamma(t) := \partial\mathcal{I}(t) = \partial\mathcal{E}(t)$

Continuity of the **surface elevation** and of the **surface pressure**

$$\zeta(t, \cdot) = \zeta_i(t, \cdot) \quad \text{and} \quad \underline{P}(t, \cdot) = \underline{P}_i(t, \cdot) \quad \text{on} \quad \Gamma(t)$$

## Coupling(s)

Interior/Exterior coupling on  $\Gamma(t) := \partial\mathcal{I}(t) = \partial\mathcal{E}(t)$

Continuity of the **surface elevation** and of the **surface pressure**

$$\zeta(t, \cdot) = \zeta_i(t, \cdot) \quad \text{and} \quad \underline{P}(t, \cdot) = \underline{P}_i(t, \cdot) \quad \text{on} \quad \Gamma(t)$$

## Fluid/Solid coupling

Newton's equations:

$$\begin{cases} m\dot{U}_G & = -mg\mathbf{e}_z + \int_{l(t)} (P_i - P_{\text{atm}}) \mathbf{N}_w, \\ \frac{d}{dt}(\mathcal{I}\omega) & = \int_{l(t)} (P_i - P_{\text{atm}}) \mathbf{r}_G \times \mathbf{N}_w. \end{cases}$$

# Summary of the general approach

- ① Euler equations with
  - ▶ Free surface, constrained pressure in the exterior domain
  - ▶ Constrained surface, free pressure in the interior domain
- ② Coupling conditions at the contact line
- ③ Fluid/solid coupling via Newton's equations

# Summary of the general approach

- 1 Euler equations with
  - ▶ Free surface, constrained pressure in the exterior domain
  - ▶ Constrained surface, free pressure in the interior domain
- 2 Coupling conditions at the contact line
- 3 Fluid/solid coupling via Newton's equations

## Remark

*The same approach can be used with (simpler) asymptotic models:*

- 1 *1D shallow water models*
  - ↪ *Free boundary problem for the contact line*
- 2 *1D shallow water models and vertical walls*
  - ↪ *Coupling conditions at the contact line*
- 3 *1D Boussinesq models*
  - ↪ *Dispersive boundary layer*

# The one dimensional shallow water equations

In the exterior domain

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = \frac{1}{\rho} H \partial_x \underline{P}_{\text{atm}} = 0 \end{cases}$$

# The one dimensional shallow water equations

In the exterior domain

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = \frac{1}{\rho} H \partial_x \underline{P}_{\text{atm}} = 0 \end{cases}$$

In the interior domain  $\mathcal{I} = (x_-(t), x_+(t))$

$$\begin{cases} \partial_x Q_i = -\partial_t H_i, \\ \partial_t Q_i + \partial_x \left( \frac{1}{H_i} Q_i^2 + \frac{1}{2} g H_i^2 \right) = -\frac{1}{\rho} H_i \partial_x \underline{P}_i. \end{cases}$$

# The one dimensional shallow water equations

In the exterior domain

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = \frac{1}{\rho} H \partial_x \underline{P}_{\text{atm}} = 0 \end{cases}$$

In the interior domain  $\mathcal{I} = (x_-(t), x_+(t))$

$$\begin{cases} \partial_x Q_i = -\partial_t H_i, \\ \partial_t Q_i + \partial_x \left( \frac{1}{H_i} Q_i^2 + \frac{1}{2} g H_i^2 \right) = -\frac{1}{\rho} H_i \partial_x \underline{P}_i. \end{cases}$$

Coupling conditions at  $x = x_{\pm}(t)$

$$H(t, \cdot) = H_i(t, \cdot), \quad Q(t, \cdot) = Q_i(t, \cdot), \quad \text{and} \quad \underline{P}_{\text{atm}}(t, \cdot) = \underline{P}_i(t, \cdot).$$



# The one dimensional shallow water equations

In the exterior domain

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = \frac{1}{\rho} H \partial_x \underline{P}_{\text{atm}} = 0 \end{cases}$$

In the interior domain  $\mathcal{I} = (x_-(t), x_+(t))$

$$\begin{cases} \partial_x Q_i = -\partial_t H_i, \\ \partial_t Q_i + \partial_x \left( \frac{1}{H_i} Q_i^2 + \frac{1}{2} g H_i^2 \right) = -\frac{1}{\rho} H_i \partial_x \underline{P}_i. \end{cases}$$

Coupling conditions at  $x = x_{\pm}(t)$

$$H(t, \cdot) = H_i(t, \cdot), \quad Q(t, \cdot) = Q_i(t, \cdot), \quad \text{and} \quad \underline{P}_{\text{atm}}(t, \cdot) = \underline{P}_i(t, \cdot).$$

Coupling with the solid equations: the case of a fixed solid

$$\partial_t H_i = 0 \quad \rightsquigarrow \quad Q_i(t, x) = q_i(t)$$

## Reduction of the problem

- Interior equations

$$\begin{cases} Q(t, x) = q_i, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P}_i \end{cases}$$

with  $\underline{P}_i(t, x_{\pm}(t)) = P_{\text{atm}}$

↪ Solvability condition for  $\underline{P}_i$  ( $\int_{x_-}^{x_+} \partial_x \underline{P}_i = 0$ )

## Reduction of the problem

- Interior equations

$$\begin{cases} Q(t, x) = q_i, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P}_i \end{cases}$$

with  $\underline{P}_i(t, x_{\pm}(t)) = P_{\text{atm}}$

↪ Solvability condition for  $\underline{P}_i$  ( $\int_{x_-}^{x_+} \partial_x \underline{P}_i = 0$ )

$$\partial_t q_i = F(q_i, x_+(t), x_-(t))$$

## Reduction of the problem

- Interior equations

$$\begin{cases} Q(t, x) = q_i, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P}_i \end{cases}$$

with  $\underline{P}_i(t, x_{\pm}(t)) = P_{\text{atm}}$

↪ Solvability condition for  $\underline{P}_i$  ( $\int_{x_-}^{x_+} \partial_x \underline{P}_i = 0$ )

$$\partial_t q_i = F(q_i, x_+(t), x_-(t))$$

- The problem is reduced to

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = 0 \end{cases} \quad \text{in } E(t)$$

## Reduction of the problem

- Interior equations

$$\begin{cases} Q(t, x) = q_i, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P}_i \end{cases}$$

with  $\underline{P}_i(t, x_{\pm}(t)) = P_{\text{atm}}$

↪ Solvability condition for  $\underline{P}_i$  ( $\int_{x_-}^{x_+} \partial_x \underline{P}_i = 0$ )

$$\partial_t q_i = F(q_i, x_+(t), x_-(t))$$

- The problem is reduced to

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = 0 \end{cases} \quad \text{in } E(t)$$
  
$$\begin{cases} Q(t, x_{\pm}(t)) = q_i(t), \\ \partial_t q_i = F(q_i, x_-, x_+). \end{cases} \quad \text{(boundary condition)}$$

## Reduction of the problem

- Interior equations

$$\begin{cases} Q(t, x) = q_i, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P}_i \end{cases}$$

with  $\underline{P}_i(t, x_{\pm}(t)) = P_{\text{atm}}$

↪ Solvability condition for  $\underline{P}_i$  ( $\int_{x_-}^{x_+} \partial_x \underline{P}_i = 0$ )

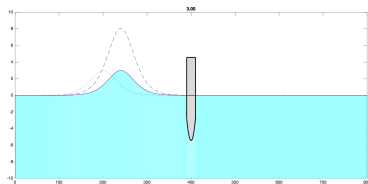
$$\partial_t q_i = F(q_i, x_+(t), x_-(t))$$

- The problem is reduced to

$$\begin{cases} \partial_t H + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = 0 \end{cases} \quad \text{in } E(t)$$
  
$$\begin{cases} Q(t, x_{\pm}(t)) = q_i(t), \\ \partial_t q_i = F(q_i, x_-, x_+). \end{cases} \quad \text{(boundary condition)}$$

$$H(t, x_{\pm}(t)) = H_i(t, x_{\pm}(t)) \quad \text{(free boundary equation)}$$

# 1D shallow water equations and vertical walls

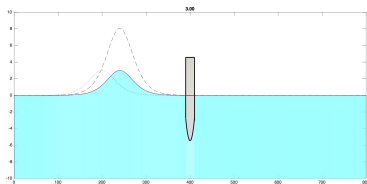


Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

Equations in the exterior and interior domains

Unchanged: standard NSW equations (with pressure source term in  $\mathcal{I}$ )

# 1D shallow water equations and vertical walls



Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

## Equations in the exterior and interior domains

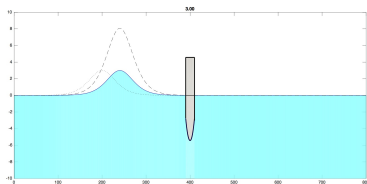
Unchanged: standard NSW equations (with pressure source term in  $\mathcal{I}$ )

## Coupling conditions at $x = \pm R$

$$H(t, \cdot) \Big|_{x=R} = H_i(t, \cdot) \Big|_{x=R}, \quad Q(t, \cdot) = Q_i(t, \cdot), \quad \text{and} \quad P_{\text{atm}}(t, \cdot) \Big|_{x=R} = P_i(t, \cdot) \Big|_{x=R}.$$



# 1D shallow water equations and vertical walls



Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

Equations in the exterior and interior domains

Unchanged: standard NSW equations (with pressure source term in  $\mathcal{I}$ )

Coupling conditions at  $x = \pm R$

$$H(t, \cdot) = H_i(t, \cdot), \quad Q(t, \cdot) = Q_i(t, \cdot), \quad \text{and} \quad P_{\text{sym}}(t, \cdot) = P_i(t, \cdot).$$

Coupling with the solid equations: the case of a fixed solid

Unchanged

# Non Vertical vs Vertical walls

## Non vertical walls

- Continuity of  $Q$   $\rightsquigarrow$  Boundary condition for the exterior equations
- Continuity of  $H$   $\rightsquigarrow$  Evolution equation for  $x_{\pm}$
- Continuity of  $P$   $\rightsquigarrow$  Evolution equation for  $q_i$

## Vertical walls

- Continuity of  $Q$   $\rightsquigarrow$  Boundary condition for the exterior equations
- ~~Continuity of  $H$~~   $\rightsquigarrow x_{\pm} = \pm R$  are fixed!
- ~~Continuity of  $P$~~   $\rightsquigarrow$  Evolution equation for  $q_i$  ????

$$\begin{cases} \partial_t \zeta + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P} \end{cases}$$

with  $\underline{P} = P_{\text{atm}}$  in  $\mathcal{E}$  and  $\underline{P} = P_i$  in  $\mathcal{I}$ .

$$\begin{cases} \partial_t \zeta + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P} \end{cases}$$

with  $\underline{P} = P_{\text{atm}}$  in  $\mathcal{E}$  and  $\underline{P} = P_i$  in  $\mathcal{I}$ .

- Local conservation of energy

$$\partial_t \mathfrak{e} + \partial_x \mathfrak{F} = 0$$

with

$$\mathfrak{e} = \frac{1}{2} \left( g \zeta^2 + \frac{1}{H} Q^2 \right) \quad \text{and} \quad \mathfrak{F} = Q \left( \zeta + \frac{1}{2} \frac{Q^2}{h^2} \right)$$

$$\begin{cases} \partial_t \zeta + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P} \end{cases}$$

with  $\underline{P} = P_{\text{atm}}$  in  $\mathcal{E}$  and  $\underline{P} = P_i$  in  $\mathcal{I}$ .

- Local conservation of energy

$$\partial_t \mathfrak{e} + \partial_x \mathfrak{F} = 0$$

with

$$\mathfrak{e} = \frac{1}{2} (g \zeta^2 + \frac{1}{H} Q^2) \quad \text{and} \quad \mathfrak{F} = Q \left( \zeta + \frac{1}{2} \frac{Q^2}{h^2} \right)$$

- Total Energy

$$E_{\text{tot}} = \int_{\mathcal{E}} \mathfrak{e} + \frac{1}{2} \int_{\mathcal{I}} \left( g \zeta_w^2 + \frac{q_i^2}{h_w} \right)$$

$$\begin{cases} \partial_t \zeta + \partial_x Q = 0, \\ \partial_t Q + \partial_x \left( \frac{1}{H} Q^2 + \frac{1}{2} g H^2 \right) = -\frac{1}{\rho} H \partial_x \underline{P} \end{cases}$$

with  $\underline{P} = P_{\text{atm}}$  in  $\mathcal{E}$  and  $\underline{P} = P_i$  in  $\mathcal{I}$ .

- Local conservation of energy

$$\partial_t \mathbf{e} + \partial_x \mathfrak{F} = 0$$

with

$$\mathbf{e} = \frac{1}{2} \left( g \zeta^2 + \frac{1}{H} Q^2 \right) \quad \text{and} \quad \mathfrak{F} = Q \left( \zeta + \frac{1}{2} \frac{Q^2}{h^2} \right)$$

- Total Energy

$$E_{\text{tot}} = \int_{\mathcal{E}} \mathbf{e} + \frac{1}{2} \int_{\mathcal{I}} \left( g \zeta_w^2 + \frac{q_i^2}{h_w} \right)$$

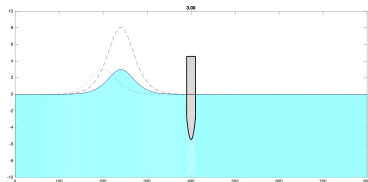
- Conservation of total energy

$$0 = \llbracket \mathfrak{F} \rrbracket + \alpha q_i \dot{q}_i$$

- Evolution equation for  $q_i$

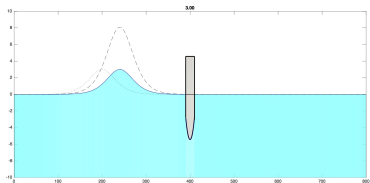
$$\alpha \dot{q}_i = -\llbracket \zeta + \frac{1}{2} \frac{q_i^2}{h_w^2} \rrbracket.$$

## Including dispersive effects using a Boussinesq model



Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

## Including dispersive effects using a Boussinesq model



Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

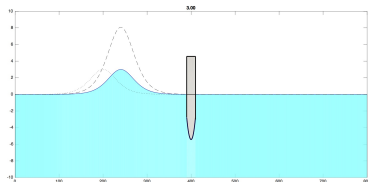
$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \varepsilon \partial_x (\frac{1}{h_0} q^2) + h \partial_x \zeta = -h \partial_x \underline{P} \end{cases}$$

with

$$\begin{cases} \underline{P} = P_{\text{atm}} & \text{on } \mathcal{E} = (-\infty, -R) \cup (R, \infty), \\ \zeta = \zeta_w(x) & \text{on } \mathcal{I} = (-R, R), \end{cases}$$



# Including dispersive effects using a Boussinesq model



Fixed object with vertical  
sidewalls at  $x_{\pm} = \pm R$

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta = -h \partial_x \underline{P} \end{cases}$$

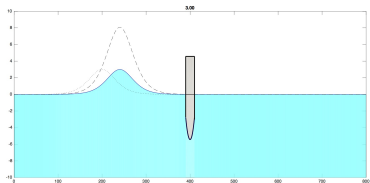
with

$$\begin{cases} \underline{P} = P_{\text{atm}} & \text{on } \mathcal{E} = (-\infty, -R) \cup (R, \infty), \\ \zeta = \zeta_w(x) & \text{on } \mathcal{I} = (-R, R), \end{cases}$$

and **one** coupling condition

$$q(t, \pm R) = q_i(t).$$

## Including dispersive effects using a Boussinesq model



Fixed object with vertical sidewalls at  $x_{\pm} = \pm R$

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \varepsilon \partial_x (\frac{1}{h_0} q^2) + h \partial_x \zeta = -h \partial_x \underline{P} \end{cases}$$

with

$$\begin{cases} \underline{P} = P_{\text{atm}} & \text{on } \mathcal{E} = (-\infty, -R) \cup (R, \infty), \\ \zeta = \zeta_w(x) & \text{on } \mathcal{I} = (-R, R), \end{cases}$$

and **one** coupling condition

$$q(t, \pm R) = q_i(t).$$

and, **with an energy conservation argument,**

$$-\alpha \dot{q}_i = \llbracket \zeta + \varepsilon \frac{1}{2} \zeta^2 - \delta^2 \partial_x \partial_t q \rrbracket$$

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

①  $[[q]] = 0$

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
  - 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$
-

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
- 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$

- 
- Denote  $R_0$  the inverse of  $(1 - \delta^2 \partial_x^2)$  with **Dirichlet** BC at  $x = \pm R$ ,

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
- 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$

- 
- Denote  $R_0$  the inverse of  $(1 - \delta^2 \partial_x^2)$  with **Dirichlet** BC at  $x = \pm R$ ,

$$\partial_t q = -R_0 \Gamma + \dot{q}_i \exp\left(-\frac{1}{\delta} |x|_R\right)$$

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
- 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$

- 
- Denote  $R_0$  the inverse of  $(1 - \delta^2 \partial_x^2)$  with **Dirichlet** BC at  $x = \pm R$ ,

$$\partial_t q = -R_0 \Gamma + \dot{q}_i \exp\left(-\frac{1}{\delta} |x|_R\right)$$

- $\partial_t \partial_x q(\pm R) = -\partial_x R_0 \Gamma \mp \frac{1}{\delta} \dot{q}_i$



## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
- 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$

- 
- Denote  $R_0$  the inverse of  $(1 - \delta^2 \partial_x^2)$  with **Dirichlet** BC at  $x = \pm R$ ,

$$\partial_t q = -R_0 \Gamma + \dot{q}_i \exp\left(-\frac{1}{\delta} |x|_R\right)$$

- $\partial_t \partial_x q(\pm R) = -\partial_x R_0 \Gamma \mp \frac{1}{\delta} \dot{q}_i$
- $\partial_t [[\partial_x q]] = -[[\partial_x R_0 \Gamma]] - \frac{2}{\delta} \dot{q}_i$

## A transmission problem

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ (1 - \delta^2 \partial_x^2) \partial_t q + \underbrace{\varepsilon \partial_x \left( \frac{1}{h_0} q^2 \right) + h \partial_x \zeta}_{:=\Gamma} = 0 \end{cases} \quad \text{if } |x| > R$$

with **transmission conditions**

- 1  $[[q]] = 0$
- 2  $-\delta^2 \partial_t [[\partial_x q]] + [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] = -\alpha \dot{q}_i \quad \text{with } q_i(t) = q(t, \pm R).$

- 
- Denote  $R_0$  the inverse of  $(1 - \delta^2 \partial_x^2)$  with **Dirichlet** BC at  $x = \pm R$ ,

$$\partial_t q = -R_0 \Gamma + \dot{q}_i \exp\left(-\frac{1}{\delta} |x|_R\right)$$

- $\partial_t \partial_x q(\pm R) = -\partial_x R_0 \Gamma \mp \frac{1}{\delta} \dot{q}_i$
- $\partial_t [[\partial_x q]] = -[[\partial_x R_0 \Gamma]] - \frac{2}{\delta} \dot{q}_i$
- Use second transmission condition

$$\dot{q}_i = \frac{1}{\alpha + 2\delta} \left( \delta^2 [[-\partial_x R_0 \Gamma]] - [[\zeta + \varepsilon \frac{1}{2} \zeta^2]] \right)$$

## An ODE!

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ \partial_t q + R_0 \partial_x \left( \varepsilon \frac{q^2}{h} + \frac{1}{2\varepsilon} (h^2 - 1) \right) = \dot{q}_i \exp\left(-\frac{|x|_R}{\delta}\right) \end{cases}$$

with

$$\dot{q}_i = \frac{1}{\alpha + 2\delta} \left( \delta^2 \llbracket -\partial_x R_0 \Gamma \rrbracket - \llbracket \zeta + \varepsilon \frac{1}{2} \zeta^2 \rrbracket \right)$$

## An ODE!

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ \partial_t q + R_0 \partial_x \left( \varepsilon \frac{q^2}{h} + \frac{1}{2\varepsilon} (h^2 - 1) \right) = \dot{q}_i \exp\left(-\frac{|x|_R}{\delta}\right) \end{cases}$$

with

$$\dot{q}_i = \frac{1}{\alpha + 2\delta} \left( \delta^2 \llbracket -\partial_x R_0 \Gamma \rrbracket - \llbracket \zeta + \varepsilon \frac{1}{2} \zeta^2 \rrbracket \right)$$

### Remark

*Can be put in conservative form*

$$R_0 \partial_x = \partial_x R_1$$

*where  $R_1$  is the inverse of  $(1 - \delta^2 \partial_x^2)$  with Neumann BC.*

## An ODE!

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ \partial_t q + R_0 \partial_x \left( \varepsilon \frac{q^2}{h} + \frac{1}{2\varepsilon} (h^2 - 1) \right) = \dot{q}_i \exp\left(-\frac{|x|_R}{\delta}\right) \end{cases}$$

with

$$\dot{q}_i = \frac{1}{\alpha + 2\delta} \left( \delta^2 \llbracket -\partial_x R_0 \Gamma \rrbracket - \llbracket \zeta + \varepsilon \frac{1}{2} \zeta^2 \rrbracket \right)$$

### Remark

*Can be put in conservative form*

$$R_0 \partial_x = \partial_x R_1$$

*where  $R_1$  is the inverse of  $(1 - \delta^2 \partial_x^2)$  with Neumann BC.*

### Remark

*Same approach works for **generating boundary conditions**: solve the Boussinesq equations on  $(0, \infty)$  given an initial data and  $\zeta(t, x = 0)$ .*

## References:

### General approach:

- D. L. *On the dynamics of floating structures*, 2017

### Shallow water:

- 1D, non vertical walls: T. IGUCHI, D. L., *Hyperbolic free-boundary problems and applications*, 2018
- 1D, vertical walls, viscosity: D. MAITY, J. SAN MARTIN, T. TAKAHASHI, M. TUCSNAK, *Analysis of simplified model of rigid structure floating in a viscous fluid*, 2018
- 1D, relaxation approximation, E. GODLEWSKI, M. PARISOT, J. SAINTE-MARIE, F. WAHL, *Congested shallow water model: roof modelling in free surface flow*, 2018.
- 2D radial, vertical walls: E. BOCCHI, *Floating objects in shallow water with a radial symmetry*, 2018

### Boussinesq:

- Direct numerical coupling, JIANG, *Ships waves in shallow water*, 2001
- Direct numerical coupling, U. BOSI, A.P. ENGSIG-KARUP, C. ESKILSSON, M. RICCHIUTO, *An efficient unified spectral element Boussinesq model for a point absorber*, 2018
- Dispersive boundary layer approach, D. BRESCH, D. L., G. MÉTIVIER, *Waves interacting with a partially immersed obstacle in the Boussinesq regime*, 2018
- Application to generating BC: D. L. , L. WEYNANS, *Generating boundary conditions for a Boussinesq system*, 2018.

## References:

### General approach:

- D. L. *On the dynamics of floating structures*, 2017

### Shallow water:

- 1D, non vertical walls: T. IGUCHI, D. L., *Hyperbolic free-boundary problems and applications*, 2018
- 1D, vertical walls, viscosity: D. MAITY, J. SAN MARTIN, T. TAKAHASHI, M. TUCSNAK, *Analysis of simplified model of rigid structure floating in a viscous fluid*, 2018
- 1D, relaxation approximation, E. GODLEWSKI, M. PARISOT, J. SAINTE-MARIE, F. WAHL, *Congested shallow water model: roof modelling in free surface flow*, 2018.
- 2D radial, vertical walls: E. BOCCHI, *Floating objects in shallow water with a radial symmetry*, 2018

### Boussinesq:

- Direct numerical coupling, JIANG, *Ships waves in shallow water*, 2001
- Direct numerical coupling, U. BOSI, A.P. ENGSIG-KARUP, C. ESKILSSON, M. RICCHIUTO, *An efficient unified spectral element Boussinesq model for a point absorber*, 2018
- Dispersive boundary layer approach, D. BRESCH, D. L., G. MÉTIVIER, *Waves interacting with a partially immersed obstacle in the Boussinesq regime*, 2018
- Application to generating BC: D. L. , L. WEYNANS, *Generating boundary conditions for a Boussinesq system*, 2018.

# Thanks for your attention